



What is MSAM?

- New PDART task (Planetary Data Archive, Restoration and Tools)
 - Part of NASA ROSES (Research Opportunities in Space and Earth Science)
- Starting this month (June 2017)
- Run by personnel from JPL's Multimission Image Processing Lab (MIPL)
- This presentation introduces MSAM to the planetary science community
 - We solicit feedback on your specific needs



What will MSAM do?

- Create higher-order data sets using all available MSL Mastcam data
 - Stereo processing
 - Terrain meshes
 - Three types of mosaics
 - Mastcam-Navcam coregistered mosaics
 - Stereo mosaics
 - Orthorectified mosaics and DEM's
- Processing all data up to PDS Release 11
 - May go farther if budget allows
- Uses the same software and pipeline that MIPL/OPGS uses in operations
 - Well validated and robust
- Data Availability expected Aug 2018
 - All dates subject to change
- Results will be delivered to PDS



Stereo Products

- Process all ~11,900 Mastcam stereo pairs (as of PDS Release 11)
- Products created:
 - Decompanded images
 - De-Bayered (demosaicked) images
 - Disparity maps
 - XYZ point clouds
 - Surface normals
 - Range maps
 - Slope maps
 - Slope aspects
 - Stereo anaglyphs
 - Range error estimates
- These all match what MIPL/OPGS produces for the Navcams
- The following examples are Marsviewer visualizations
 - The actual data products are quantitative images (e.g. DN=XYZ value)



Stereo Product Examples



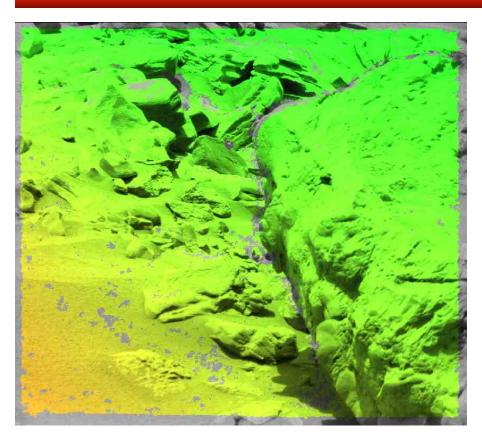
Original image (sol 735)



Decompanded (linear color space)



Stereo Product Examples (cont)

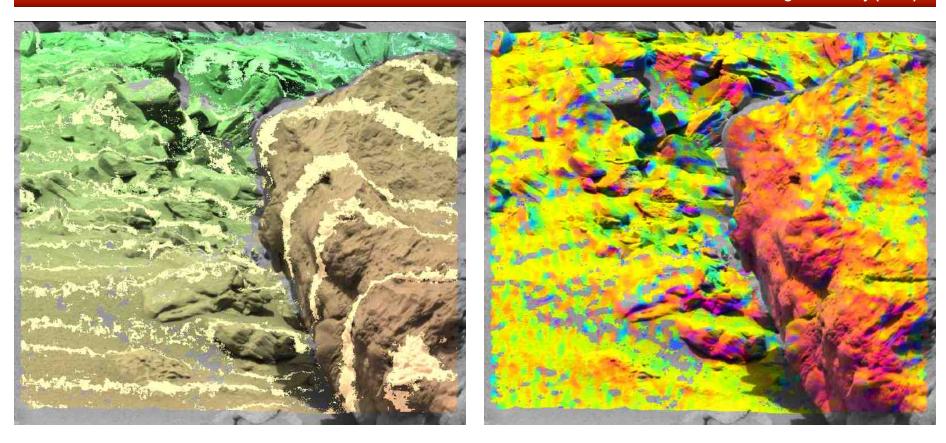


Stereo Disparity

XYZ data (contours at 10cm: red=constant X, green=constant Y, blue=constant Z)



Stereo Product Examples (cont)

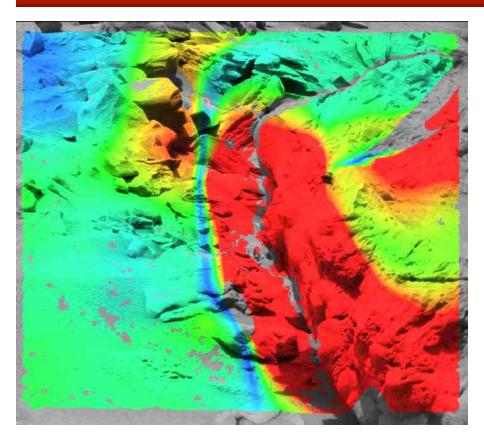


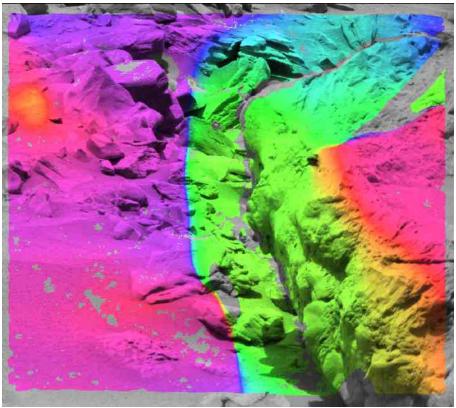
Range (contours at 10cm)

Surface normal



Stereo Product Examples (cont)





Slope

Slope Aspect (heading)

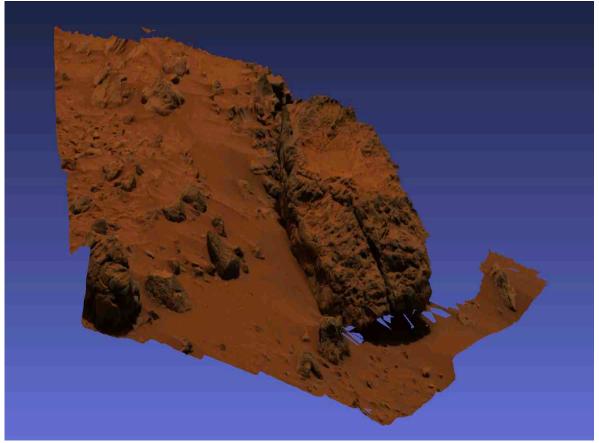


Terrain Meshes

JPL Multimission Instrument Processing Laboratory (MIPL)

- Terrain meshes will be made in OBJ format
 - Widely accepted by most 3D visualization programs (e.g. MeshLab)

 We think we have figured out how to deliver these in a PDS-4 compliant way



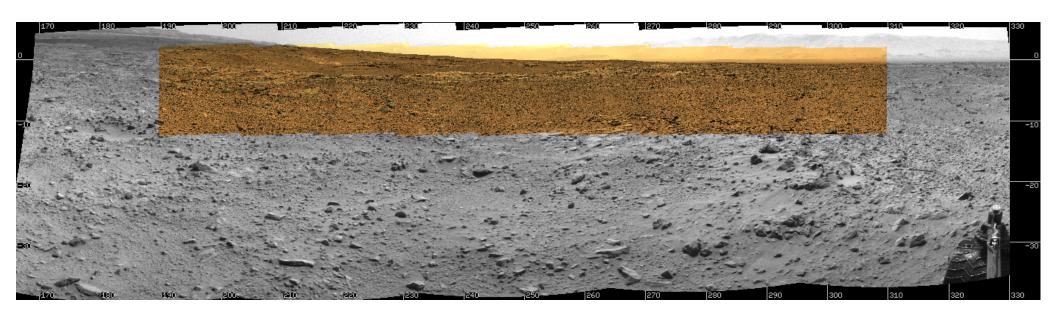


Mastcam-Navcam coregistered mosaics

- Combination of Mastcam and Navcam from the same location
 - Including non-stereo images
- Cylindrical projection
- Navcam frames serve as context images for Mastcam
- Frames will be coregistered to reduce geometric seams
- Question for the community:
 - How much Navcam context should we include?
 - May be space-prohibitive to do a full 360 at each location

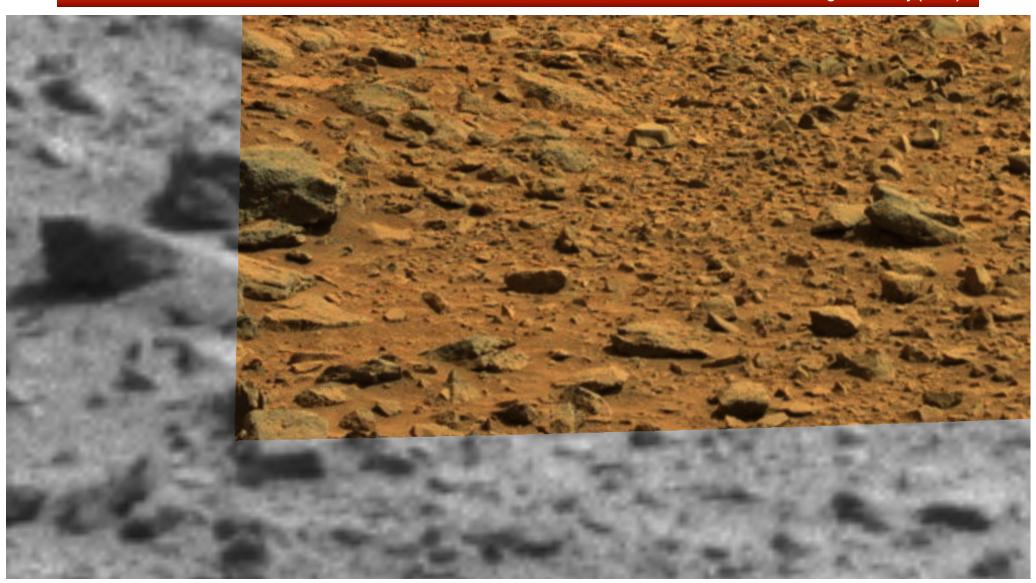


Mastcam-Navcam overview





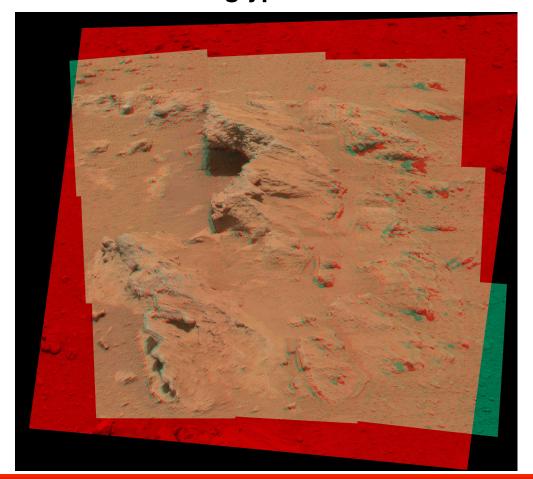
Mastcam-Navcam closeup





Stereo Mosaics

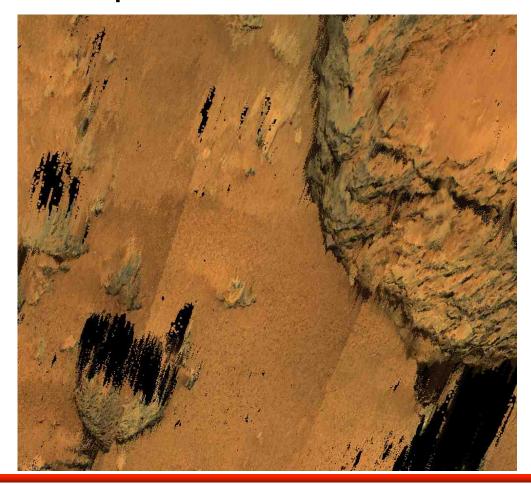
- Made from as many data sets as possible
 - Some frames not conducive to stereo viewing
- Color stereo and red/blue anaglyph





Orthorectified Mosaics and DEM's

- Orthorectified mosaics provide a "true" overhead view of the terrain
 - Uses XYZ data to remove layover effects and parallax distortion
- Coregistered DEM's provide elevation





Radiometric Correction

- Jim Bell (ASU) has an independent PDART (also starting now) to do radiometric correction of Mastcam data
 - We plan to work together to incorporate these results into MSAM mosaics and meshes
 - Radiometric correction does not affect stereo processing



Results will be delivered to PDS

- PDS 4 format
- Also compatible with the OPGS-produced Navcam archive for MSL
 - Same dual-label ODL/VICAR files
 - PDS 4 detached labels
- Question for the community:
 - Do we need to include a PDS 3 detached label as well?
 - Would exactly match PDS 3 format but not be "official" PDS 3 product
 - PDS no longer accepts new kinds of PDS 3 data
 - ODL and VICAR labels may be sufficient



PDS Peer Review

- PDS Peer Review currently planned for Dec 2017-Feb 2018
 - Dates may change!
- We will be looking for peer reviewers
- Question for the community:
 - Would you like to participate in the Peer Review?



Feedback

JPL Multimission Instrument Processing Laboratory (MIPL)

- We welcome comments, questions, suggestions, or concerns from the planetary data community
 - That's the entire point of this talk
- Please contact the lead author and PI:

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Full Team:

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- Justin Maki (JPL/MIPL), Co-I, validation
- Stirling Algermissen (JPL/MIPL), Co-I, PDS generation
- Hallie Abarca (JPL/MIPL), Co-I, mosaic generation
- Nicholas Ruoff (JPL/MIPL), Co-I, stereo pipeline
- Adrian Tinio (JPL/MIPL), pipeline
- Steve Levoe (JPL/MIPL), PDS label generation
- Costin Radulescu (JPL/MIPL), PDS integration
- Amy Culver (JPL/MIPL), PDS integration
- Nicholas Toole (JPL/MIPL), Marsviewer integration
- Ray Arvidson (Washingon University), Collaborator, science & PDS integration
- Ken Herkenhoff (USGS), Collaborator, science consultant